HIGH-SPEED SORTING ROBOT SH800



Maximum cadence 200 ppm



Arm reach 800 mm



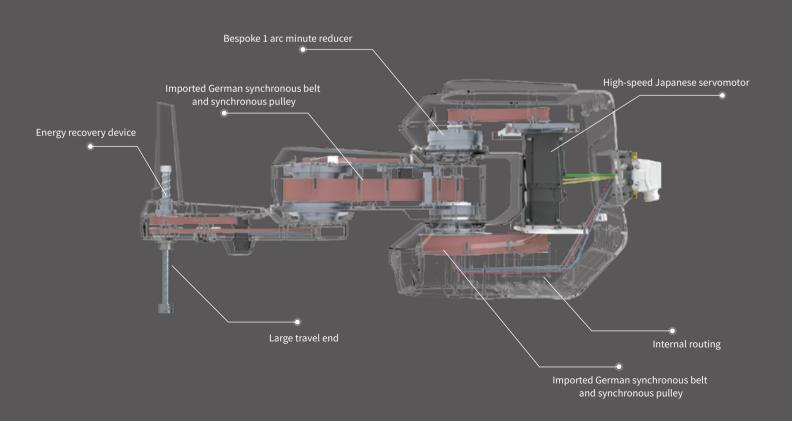
Depth 150 mm

- The Atomrobot SH800SCARA is a dedicated plane joint robot specially developed for high-speed sorting link of light and small materials, which has 4 degrees of freedom in space with translation along the X, Y and Z directions and the rotation around the Z-axis.
- The main body of moving components completely adopts ultra-light carbon fiber material, provided with innovative energy recovery design, therefore, high-speed picking / releasing performance of the robot has been significantly improved.
- The manipulator adopts pedestal-type installation, which occupies less space and enables more flexible layout, to be applicable to automatic packaging and sorting of various kinds of light materials.



CORE CONFIGURATION

- High-speed Japanese servomotor brings up to 200 ppm movement cadence
- Bespoke 1 arc minute reducer assures ±0.1mm precision
- Equipped with imported German synchronous belt and synchronous pulley, it can give more than 2 years of maintenance-free and precision holding time.



Parameter

High Speed Flexibility Simple Modularization

Model		SH800	
Degree of freedom		4	
Max Payload		2kg	
Weight		60kg	
Working radius		800mm	
Precision	Position	±0.05mm	
	Rotation	±0.05°	
Max payload inertia		0.12kg•m²	
Controller		atommotion	

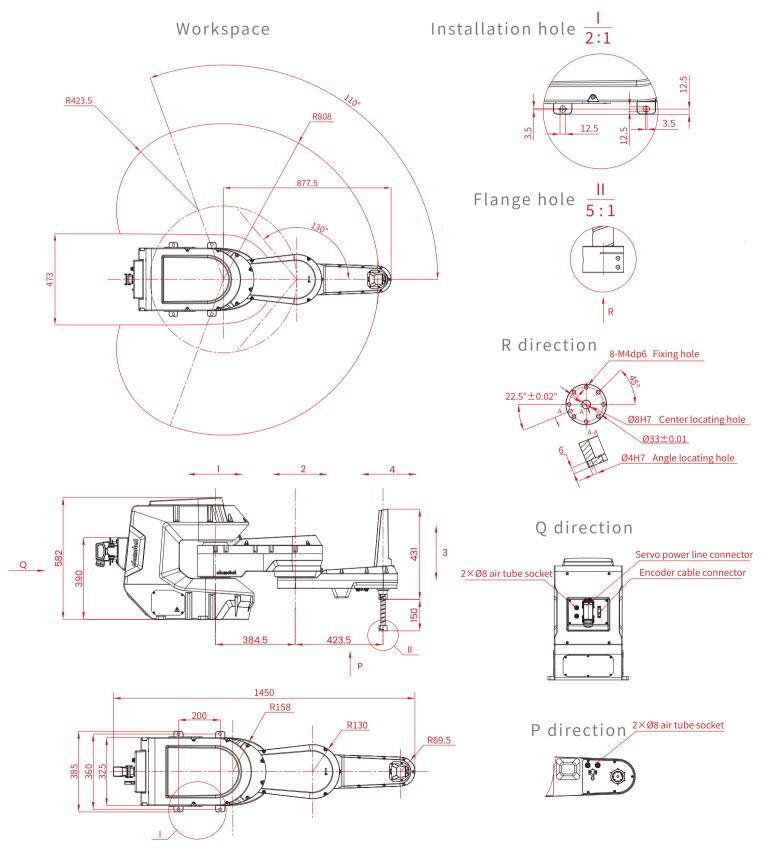
Movement range	
1-Axis ①	±110°
2-Axis ②	±130°
3-Axis ③	150mm
4-Axis ④	±360°

- © Cadence parameters are data tested in the laboratory
 The load is of standard weight, without picking / releasing actions in the process.
- ▼ Please consult us for the requirements for special service environments (dust, high-temperature, acid/alkali fog) and higher IP grade.



Installation environment				
Storage temperature	-10°C~70°C			
Working environment	-10°C~50°C RH≤80%			
Protection rating	IP55			
Power supply	Three-phase 380VAC -10%~+10% 49~61HZ			
Power capacity	6KVA			
Rated power	4.2KW			
Installation method	Installation of pedestal			

Dimension Diagram



HIGH SPEED ST SERIAL SCARA





🕼 High precision ±0.02mm

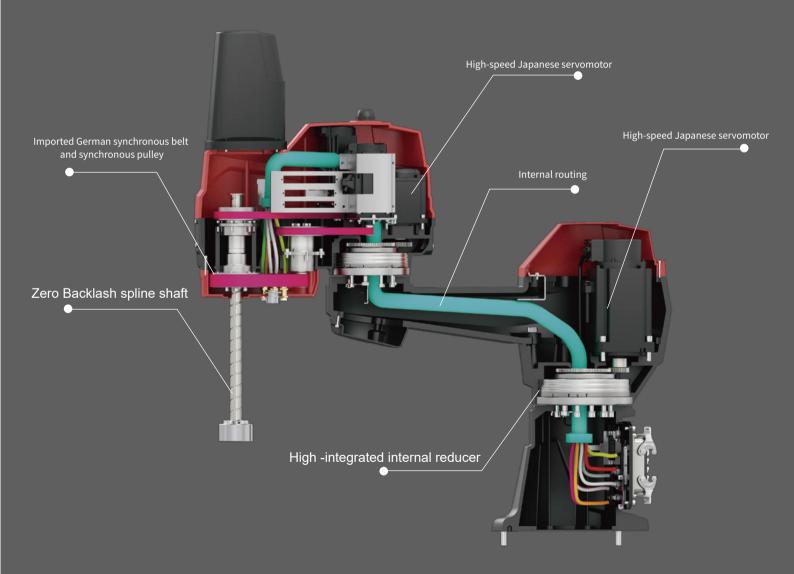
Angle range 360°

- The ST series Scara is a flat joint robot developed by Atomrobot Robot for high-speed and high -precision sorting.
- The robot arm and the reducer adopt an integrated design and use unique tooth shape. While providing large loads and high speed, the volume of the robot is greatly reduced.
- The robot adopts internal wiring, high integration, the highest protection level can reach IP65, the external interface position is diverse, available for ground and ceiling installation, suitable for various applications.



CORE CONFIGURATION

- High-speed Japanese servomotor brings up to 240 ppm movement cadence
- Bespoke 1 arc minute reducer assures ±0.02mm precision
- **■** Equipped with imported German synchronous belt and synchronous pulley, it can give more than 2 years of maintenance-free and precision holding time.



ST SERIAL

Models and Parameters







Model		ST-480-A	ST-480-B	ST-620-A		
Axes		4	4	4		
Ма	x Payload	8.4kg	8.4kg	8.4kg		
We	eight	47kg	47kg	51kg		
Str	oke	480mm 480mm		620mm		
Precision	Position	±0.02mm	±0.02mm	±0.02mm		
Precision	Rotation	±0.05° ±0.05°		±0.05°		
Max spe	ed*	240pp/min	240pp/min	220pp/min		
Max pay	load inertia	0.43kg•m²	0.43kg•m²	0.43kg•m²		
Control	ler	atommotion	atommotion	atommotion		
	1-Axis ①	±180°	±180°	±180°		
Movement	2-Axis ②	±110°	±110°	±110°		
range	3-Axis ③	±100mm	±100mm	±100mm		
	4-Axis ④	±180°	±180° ±180°			
	Storage temperature	-10°C~70°C				
	Working environment	-10°C~50°C RH≤80%				
Installation	Protection rating	IP55/IP65				
environment	Power supply	Three-phase 380VAC -10%~+10% 49~61HZ				
	Power capacity	6KVA				
	Rated power	3.6KW				
	Installation method	Ground	Ceiling	Ground		

^{*} payload2kg, 25mm-300mm-25mm Trajectory



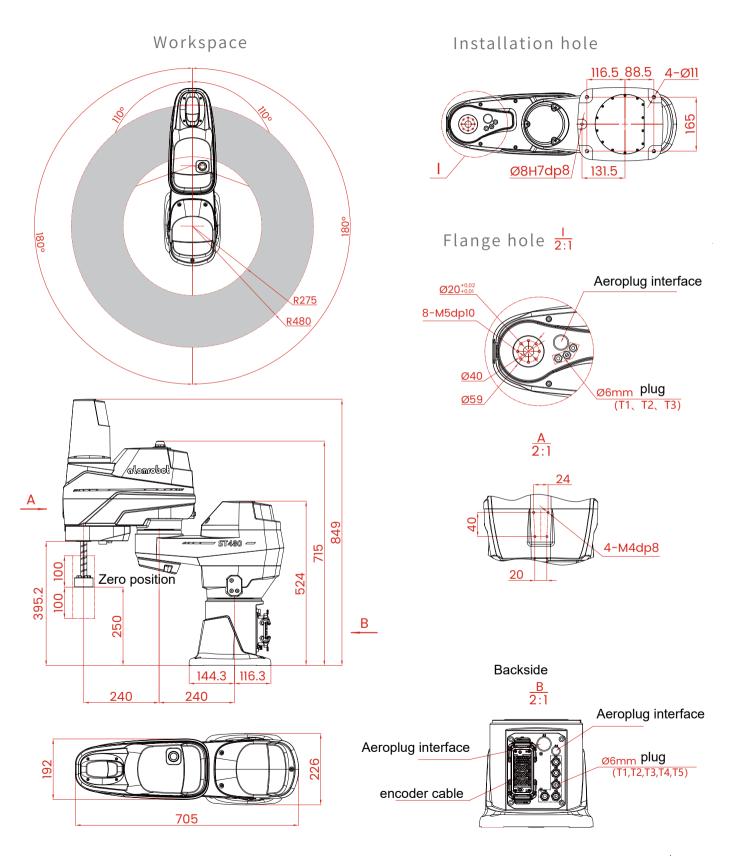
Ø Cadence parameters are data tested in the laboratory
 The load is of standard weight, without picking / releasing
 actions in the process.



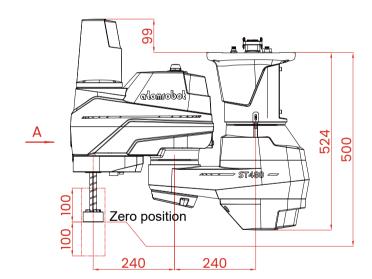


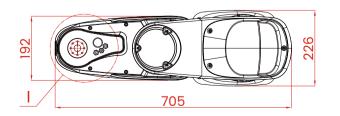


				Ι		
Model		ST-620-B	ST-800-A	ST-800-B		
Axes		4 4		4		
Max F	Payload	8.4kg 8.4kg		8.4kg		
Weig	ht	51kg	55kg	55kg		
Strok	ke .	620mm 800mm		800mm		
Precision	Position	±0.02mm	±0.02mm	±0.02mm		
Precision	Rotation	±0.05°	±0.05°	±0.05°		
Max spe	eed*	220pp/min	200pp/min	200pp/min		
Max pay	load inertia	0.43kg•m²	0.43kg•m²	0.43kg•m²		
Control	ler	atommotion	atommotion	atommotion		
	1-Axis ①	±180°	±180°	±180°		
Movement	2-Axis ②	±110°	±153°	±150°		
range	3-Axis ③	±100mm	±100mm	±100mm		
	4-Axis ④	±180°	±180°	±180°		
	Storage temperature	-10°C~70°C				
	Working environment	-10°C~50°C RH≤80%				
Installation	Protection rating	IP55/IP65				
environment	Power supply	Three-phase 380VAC -10%~+10% 49~61HZ				
	Power capacity	6KVA				
	Rated power	3.6KW				
	Installation method	Ceiling	Ground	Ceiling		



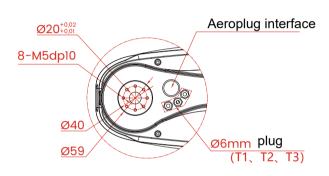
Workspace R275 R480

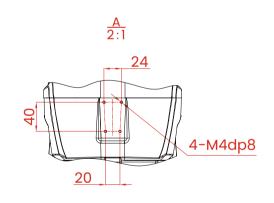


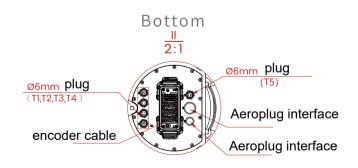


Installation hole 116.5 88.5 4-Ø11 Ø8H7dp8 131.5

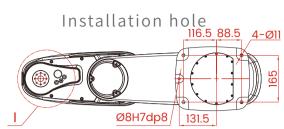
Flange hole $\frac{1}{2:1}$



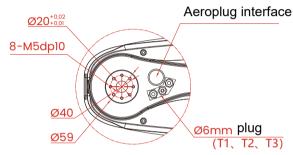


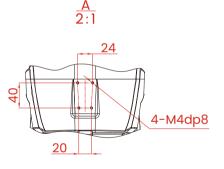


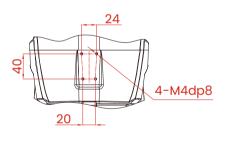
Workspace 8-M5dp10 <u>R620</u> 850 716 Zero position 395.2 250 В 144.3 | 116.3 240 380

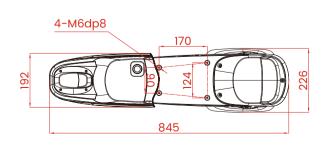


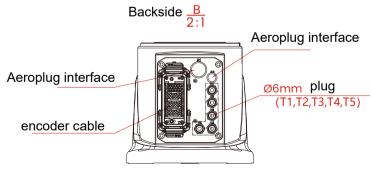






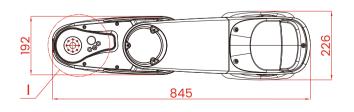




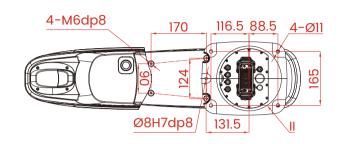


Workspace

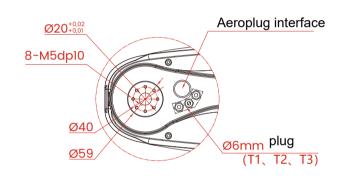
ST620 Zero position 380 240

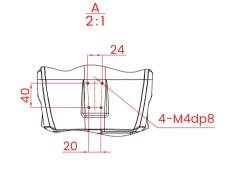


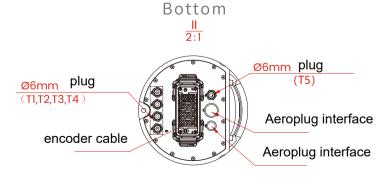
Installation hole

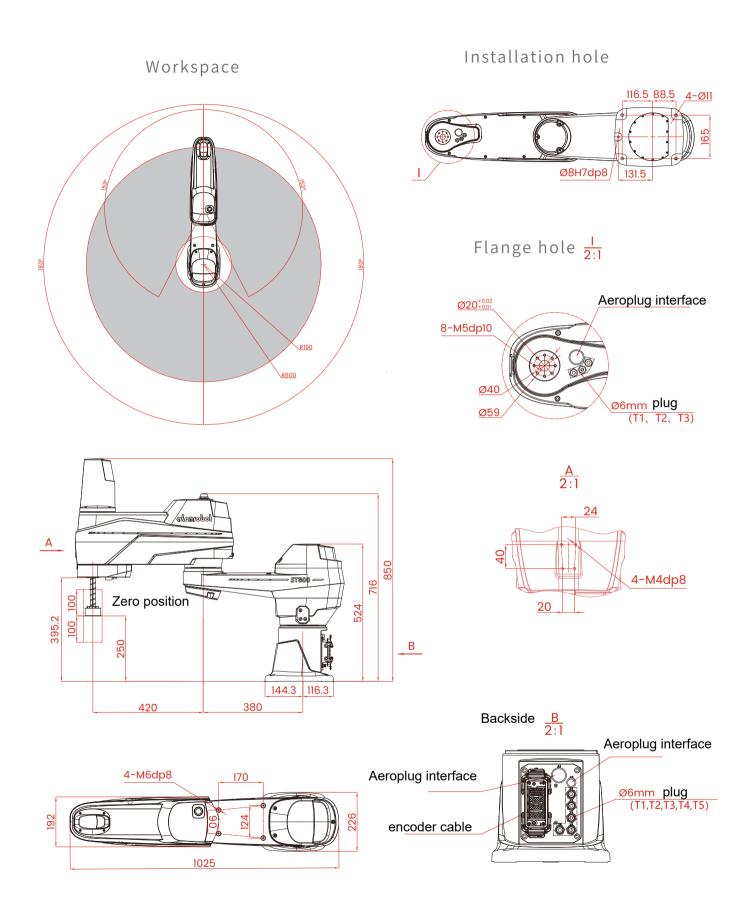


Flange hole 2:1



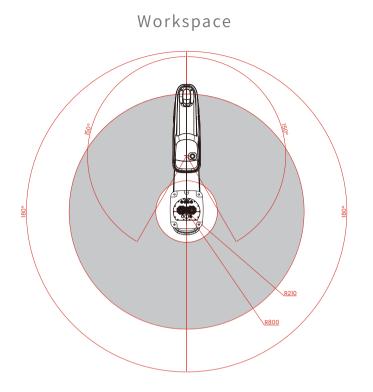




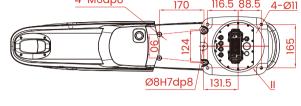


atomrobot

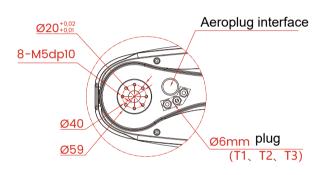
DRAWING

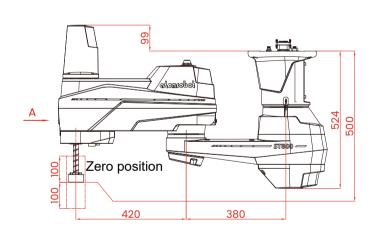


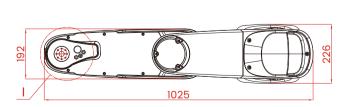
Installation hole 4-M6dp8

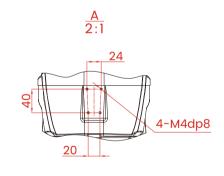


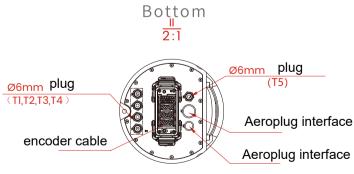
Flange hole $\frac{1}{2:1}$





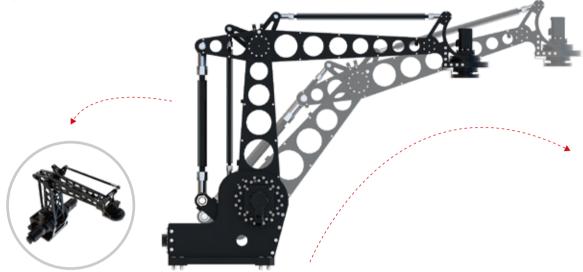






ATOM STACKING ROBOT

PT30-A



Floor Installation Design Higher working stability

The main body of arm is made of carbon fiber material, which makes it lighter

It is very applicable to the operation of large travel packing and palletizing work with small and medium loads.







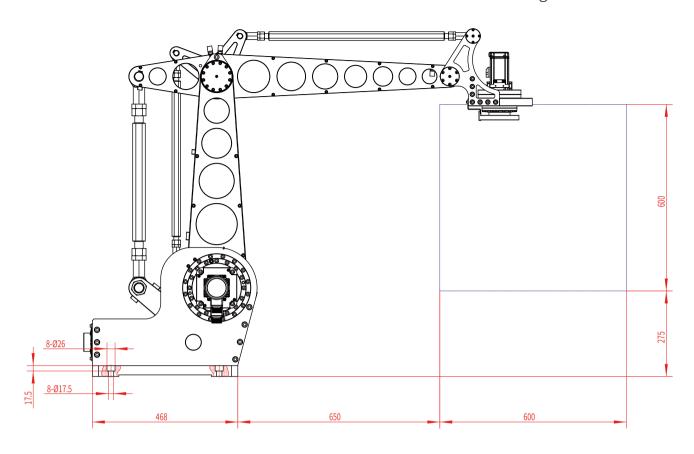


Hoisting design Lightweight

High speed Low cost

Model			PT30-A		
Axes	3		Repeatability	Position	±0.1mm
Max Payload	30	kg	кереатариту	Rotation ±0.05°	
Manipulator	Weight	120kg	Doworcupply	Three-phase 380VAC -10%~+10%, 49~61HZ	
	Workspace	600x600mm	Power supply		
	Cadence	30ppm	Power capacity	7.5KVA	
Range of Axis	X-axis	600mm	Rated power	5kw	
	Y-axis	600mm	Storage temperature	-10°C~70°C	
	X-Rot	360°	Working environment	0°C~50°C,RH≤80%	
			Protection rating	IP55	

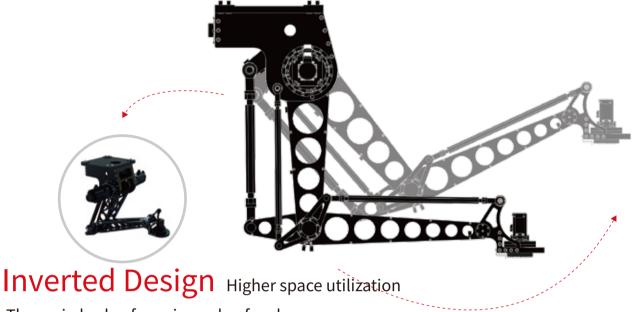
Overall Dimensions and Movement Range



Flange **Base Installation** 8-M8dp15 Uniformly distributed along the circumference Ø100 $\emptyset 25^{+0.03}_{0} dp8$ Ø125 200 348 Ø125 468

ATOM STACKING ROBOT

PT30-B



The main body of arm is made of carbon fiber material, which makes it lighter

It is very applicable to the operation of large travel packing and palletizing work with small and medium loads.









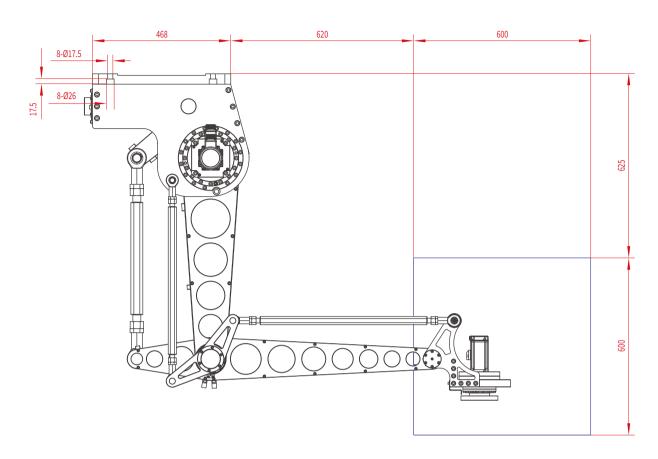
Hoisting design Lightweight

High speed

Low cost

Model			РТ30-В		
Axes	3		Repeatability	Position	±0.1mm
Max Payload	30	kg	Repeatability	Rotation	±0.05°
Manipulator	Weight	120kg	Dawaranah	Three-phase 380VAC -10%~+10%, 49~61HZ	
	Workspace	600x600mm	Power supply		
	Beat	30ppm	Power capacity	7.5KVA	
	X-axis	600mm	Rated power	5kw	
Range of Axis	Y-axis	600mm	Storage temperature	-10°C~70°C	
	X-Rot	360°	Working environment	0°C~50°C,RH≤80%	
			Protection rating	IP55	

Overall Dimensions and Movement Range





Base Installation

